

### **SPECIFICATIONS**

Item No.: ACA2400

Description: High Accuracy Digital Type Dual-Axis Inclinometer

with Full Temperature Compensation

#### **Production implementation standard reference**

- Enterprise quality system standards: ISO9001: 2008 standard (certification number: 128101)
- Tilt sensor production standards: GB / T 191 SJ 20873-2003 inclinometer general specification of Level
- •The Academy of metrology and quality inspection Calibrated in accordance to: JJF1119-2004 Electronic Level calibration Specification
- Gyro accelerometer test standard: QJ 2318-92 Gyro accelerometer test methods
- Software development reference standard: GJB 2786A-2009 military software development General requirements
- Product environmental testing standards: GJB150
- Electromagnetic anti-interference test standards: GB / T 17626
- Version: Ver.10Date:2016.10.27





#### **General Description**

ACA2400 is a analog balanced servo inclinometer which manufactured by Rion company, the principle is composed of the non-contact displacement sensor, torque motor, error & amplifier circuit, the feedback circuit and cantilever mass five parts. This series inclinometer accuracy is far superior than the inclinometer relative to the electrolyte principle or the capacitance principle on the nonlinearity,repeatability, hysteresis, temperature drift and working temperature, resistance shock anti-vibration and other properties.Internal integration of the 24 ARM high-end system,resolution 0.0005°, precision 0.005°, temperature drift: 0.0008°C/°, it is a highly competitive industry product nowadays.Non-contact installation features make ACA2400 with superior system integration, Simply fix the sensor on the measured surface by screws, then can automatically calculate the object posture inclination, easy to use, no need to find the relative change two surfaces for mounting. With strong ability resistance to external electromagnetic interference and to withstand shock and vibration, in the domestic counterparts products with absolute competitive advantage, specialized in application in the industrial and military fields where the high-end user requirements.

#### **Features**

- Dual-Axis Inclinometer
- •Response frequence: 50Hz
- Wide temperature working: -40~+85℃
- Size: L110×W65×H32mm
- RS485, TTL are optional
- IP67 Protection

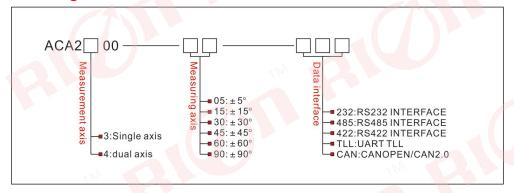
#### Application:

- Engineering vehicles automatic leveling
- Precise equipment level control
- Underground drill posture navigation
- Based on the angle direction measurement

- Measuring Range :±1~±90° optional
- Wide voltage input: 9~36V
- Resolution: 0.0005°
- ZERO Temp. Drift ±0.0008
- Water-proof air-plug
- •Bridge & dam detection
- Medical facilities angle control
- Railway gauging rule, gauge equipment leveling
- •Geological equipment inclined monitoring
- Directional satellite communications antenna pitching angle measurement



### **Ordering information:**



E.g: ACA2400-05-232: Dual-axis/±5°Measuring range/RS232 output

### **Technical Data**

Parameters	Conditions	ACA2400T-05	ACA2400T-10	ACA2400T-15			
Measuring range	Conditions	±05	±10	±15	•		
Measuring axis		X, Y	X, Y	X, Y			
Resolution	77	0.0005	0.0005	0.0005	0		
Absolute			0.000	<del>a( // /</del>	197		
accuracy	<b>@25</b> ℃	0.003	0.005	0.006	٥		
Long term					0		
stability		0.002	0.003	0.005			
Zero							
temperature	-40~85°	±0.0008	±0.0008	±0.0008	°/°C		
coefficient	100			400			
Sensitivity			<u> </u>				
temperature	-40~85°	≤50	≤50	≤50	ppm/℃		
coefficient			_ ( /	12			
Power on time		0.5	0.5	0.5	S		
Response time		0.005	0.005	0.005	S		
Output rate	5Hz、15Hz、35Hz、50Hz can be set						
Out signal	RS232/RS485/RS422/TTL/CAN						
Electromagnetic		41 / /					
compatibility		According	to EN6100 and GB	11/626			
MTBF		≥5	0000 hou <mark>rs / tim</mark> es	10			
Insulation	N100 M						
Resistance	≥100 M						
Shockproof	100g@11ms、imes/Axis(half sinusoid)						
Anti-vibration	10grms、10~1000Hz						
Protection glass			IP67				
Cables	Standard 1M length、wearproof、wide temperature、						
Gabics	Shielded cables4*0.4mm2 air-plug connector						
Weight	150g(without cable)						

#### **Electronic Characteristics**

Parameters	Conditions	Min	Standard	Max	Unit
Power supply	Standard	9	24	36	V
	customized	800	Other voltage		V
Working current	No-load	100	50		mA
Working temperature		-40		+85	℃
Store temperature	7	-55		+100	°C

#### Key words:

Resolution: Refers to the sensor in measuring range to detect and identify the smallest changed value.

Absolute accuracy: Refers to in the normal temperature circumstances, the sensor absolute linearity, repeatability, hysteresis, zero deviation, and transverse error comprehensive error.

Long term stability: Refers to the sensors in normal temperature conditions, the deviation between the maximum and minimum values after a year's long time work.

Response time: Refers to the sensor in an angle change, the sensor output value reached the standard time required.

#### **Mechanical Parameters**

Connectors: 1m cable with air-plug connector (customized)

Protection glass: IP67(air plug connector)

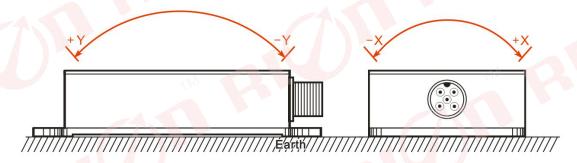
o Enclosure material : Aluminum Shield Oxide

o Installation: 4\*M5 screws



#### **Measuring Directions&Fix**

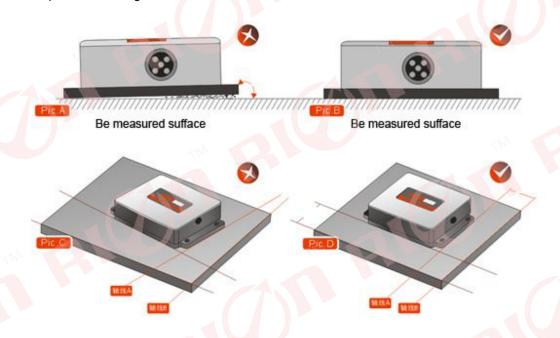
The installation must guarantee the product bottom is parallel to measured face, and reduce the influence of dynamic and acceleration to the sensor. This product can be installed horizontally or mounted vertically (mounted vertically selection is only applicable to the single axis), for installation please refer to the following scheme.



#### **Production installation notes:**

Please follow the correct way to install tilt sensor, incorrect installation can cause measurement errors, with particular attention to the "surface", "line":: 1) The Sensor mounting surface and the measured surface must be fixed closely, smoothly, stability,if mounting surface uneven likely to cause the sensor to measure the angle error. See Figure Pic.AB

2) The sensor axis and the measured axis must be parallel ,the two axes do not produce the angle as much as possible. See Figure Pic.CD

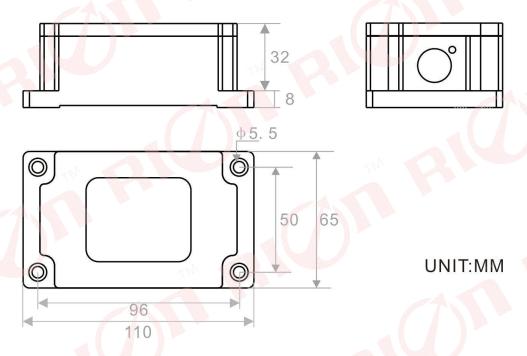


#### **Electrical Connection**

Line	BLACK	WHITE	BLUE	BROWN	GRAY
color	GND	RS232(RXD)	RS232(TXD)	<mark>Vcc</mark> 9∼36V	FACTORY
function	Power Negative	Or RS485(D+)	Or RS485(D-)	Power supply positive	Use only



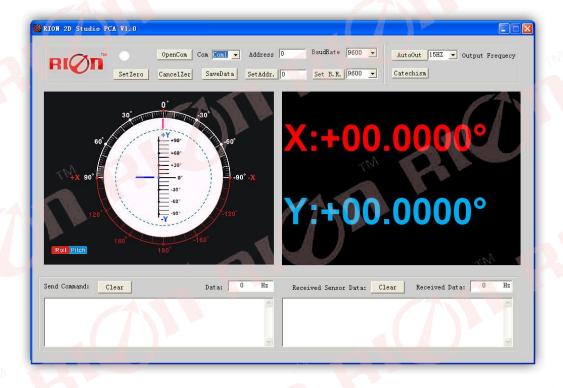
#### **Dimension**



Size: L110×W65×H40mm

#### **RION serial port tester software**

You can download the RION angle debugging software from RION's official website for the preliminary angle debugging, also you Can download public version of the serial port assistant software on line for using .



Open/Close: Open and close COM port;

Com: Select the the device corresponding to the COM port

Address: Fill in the sensor current address code, the factory default is 00

Set Address: Set the sensor address code input box on the right to enter the desired address code, click Set Addr button

Save Data: Save the data, click here data can be synchronized Save angle data, the file is stored by default in the C: ---- COMDATA file

Set Zero: Set relative zero, the sensor current angle is 00.00 degrees

Cancel Zero: Unset the relative zero, to restore the sensor to the factory absolute zero;

Baud Rate: Select the sense baud rate, the factory default is 9600;

Set Baud Rate: Set the sensor baud rate, on the right of the selection box to select corresponding baud rate then click SetB.R. button;

Auto Output: Switch the sensor to automatically output mode, in the automatic output mode can be filled with different output frequency in Hz;

Catechism: The sensor switch to answer pattern, such as choosing the answer type, must input "send command" (command, please refer to the specification ) on the left of "Send Command" input box, but also can fill in the transmit frequency in the Send Data, the unit Hz;

Note: after install the RION's debugging software, if can not open, please operate by the following steps (please appear to the administrator status to operate):

- 1) Copy these three files mscomm.srg、mscomm32.ocx、mscomm32.dep from the folder to C:/Windows/system32 path below。
- 2) Click "Start" -"run" --regsvr32 mscomm32.ocx, You are prompted to install successful dialog.

#### **Product Protocol**

#### 1.DATA FRAME FORMAT:

(8 bits date, 1 bit stop, No check, Default baud rate 9600)

Identifier	Date Length	Address code	Command word	Date domain	Check sum
(1byte)	(1byte)	(1byte)	(1byte)	J.	(1byte)
68		2.00			

Date format: hexadecimal

Identifier: Fixed68

Data length: From data length to check sum (including check sum) length

Address code: Accumulating module address, Default:00

Date domain will be changed according to the content and length of command word

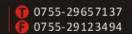
Check sum: Data length, Address code, Command word and data domain sum, No carry.

### 二、COMMAND word analysis

Desc.	Meaning/Example	Description
0X01	read X axis angle command eg: 68 04 00 01 05	data field(0 byte) no data field command
0X81	sensor responds eg: 68 07 00 81 10 26 87 60	data field(4 byte) SS AA BB BB, data field is 4 bytes responding angle value(BCD compressed

	A5	code), SS is sign bit(00 is positive, 10 is negative), AA is two digit integer value, BBBB is three digit decimal, other axis data is the same. eg: 10268760 indicates -26.8760 deg
0X02	responding command read Y axis angle E.g: 68 04 00 02 06	data field(0 byte) no data field command
0X82	sensor responds read Y axis angle eg 68 07 00 82 00 16 25 05 C9	4 bytes responding angle value(BCD compressed code), SS is sign bit(00 is positive, 10 is negative), AA is two digit integer value, BBBB is three digit decimal. other axis data is the same.  eg: 00162505 indicates +16.2505 deg
0X04	Meanwhile read angle command E.g: 68 04 00 04 08	Data domain(0byte) No Data domain command
0X84	sensor data response E.g: 68 10 00 84 00 00 20 08 10 00 25 28 10 35 00 80 DE	Data field(9byte) 68 is prefix of data packets, fixed. 10 is data lenght, fixed. 00 is address code, revisable. 84 is command code, fixed. 00 00 20 08 the four red bytes are the X axis returned angle value in compact BCD code. the high order 0 of first byte is sign bit(0: positive; 1: negative), 00 0 are three digit integer value, 20 08 are four decimal digit. other axis data analysis method is similar. the angle is +000.2008 deg by analizing. 10 00 25 28 the four blue bytes are Y axis returned angle value, analysis method is similar to X axis 10 35 00 80, the four green bytes are internal temperature value, analysis method is similar to X axis. DE check sum, hexadecimal sum of all data, exclude prefix 68, if surpass one byte, pick
0X05	Setting relative/absolute ZERO: Can set the current angle to Zero degree, relative measurement, can also be set to absolute ex-factory zero, power off save  E.g: 68 05 00 05 00 0A	Data domain (1byte) 00: absolute ZERO 01: relative ZERO
0X85	Sensor answer reply command E.g: 68 05 00 85 00 8A	Data domain (1byte)  Data domain in the number means the sensor response





97	(M)	
		results
		00 Setting successfully
	/ / \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	FF Setting failure
0X0B	Setting communication rate	Data domain (1byte)
	E.g: 68 05 00 0B 03 13	Baud rate: default :9600
8-16	The command setting is effective	00 means 2400
10	after power off then restart	01 means 4800
	( power off with save function)	02 means 9600
		03 means 19200
		04 means 38400
	400	05 means 115200
0X8B	Sensor answer reply command	Data domain (1byte)
	E.G:68 05 00 8B 90	Data domain in the number means the sensor response
		results
		00 Success FF Failure
OXOC	Setting sensor output mode	Data domain
JAUC	Response rule;	(1byte) Factory default: 00
	Need upper computer send	00 Answer reply mode
	reading angle command, the	01 5Hz Automatical output mode
	sensor answer	02 15Hz Automatical output mode
	the corresponding angle	03 25Hz Automatical output mode
	Automatic output rule:	04 35Hz Automatical output mode
	The sensor with power on can	05 50Hz Automatical output mode
	Automatically output X angle ,	06 100 Hz Automatical output mode
	output frequency is 20HZ	07 200Hz Automatical output mode
	(Power off with save function)	08 300Hz Automatical output mode
0X8C	E.g: 68 05 00 0C 00 11  The sensor answer reply	Data domain (1byte)
OXOC	command	
		Data domain in the number means the sensor response
	E.g: 68 05 00 8C 00 91	results
		00 Success FF Failure
0X0F	Setting module address	Data domain
	command	(1byte) XX Module address
	The sensor default address is 00,	Address from 00 to EF range
	1, such as a plurality of sensor	Note: All products have a common address :FF,
	to be connected with a bus cable,	If forget the address what has been set during
	e.g RS485. <mark>requires each sens</mark> or	operation , can use FF addr <mark>ess to operate the</mark>
	is set to a different address, in	product can still normally res <mark>po</mark> nd
	order to achieve control and	
	response angle .	
	2, If successfully changed the	
	new address, follow all of the	100
	commands and responding	
	Packet address code has to	
	switch to the new address code	
	which already changed then to be	
	effective, otherwise the sensor will	
	effective, otherwise the sensor will not respond to commands.(power	100

P	E.g: 68 05 00 0F 01 15 Setting the address to 01 68 05 FF 0F 00 13 Use the common address to reset address to 00	
0X8F	The sensor answer reply	Data domain (1byte),
	E.g: 68 05 00 8F 94	Data domain in the number means the sensor response
		results
	<u> </u>	00 Success FF Failure
0X0D	Query relative/absolute ZERO	Data domain (0byte)
	Used to query the sensor current	No data domain commands
	ZERO mode is relative ZERO	
	or absolute ZERO	
	E.g : 68 04 00 0D 11	
0X8D	The sensor answer reply	Data domain (1byte) ,
	command	Data domain in the number means the sensor response
	E.g: <b>68 05 00 8D 00 92</b>	results
		00 Absolute ZERO
		01 Relative ZERO

### (RION Inclinometer data format)

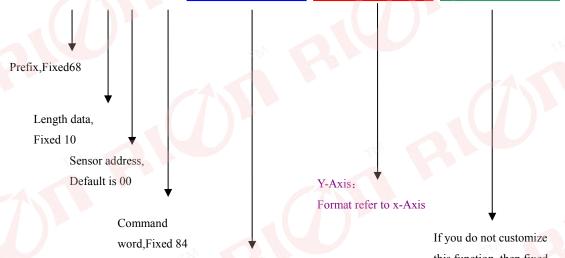
Baud rate: (9600, 8 data bits, 1data top, No check)

For example:

X-Axis: +02.0103° Y-Axis: -00.5132°

Temp: +50.500°

68 10 00 84 <u>00 02 01 03</u> <u>10 00 51 32</u> <u>00 50 50 00</u> 93



X Axis angle:

The first byte is the sign bit,00 indicates Positive angle ,10 indicates negative angle .

The second byte is the integer bit of angle, is compressed BCD code.

The third byte is decimal bytes, is compressed BCD code..

The forth byte is decimal bytes, is compressed BCD code.

this function, then fixed three bytes of 00000000, Temperature data: The first byte is the sign bit, 00 indicates the positive temperature, and the 10 represents the negative temperature Second bytes is integer bit of the temperature, is compressed BCD code Third bytes is Decimal of the temperature, is compressed BCD code Fourth bytes are reserve

The last byte is the sum of all previous data and, If carry ,Get low data.

More products information, please refer to the company's Website: <a href="https://www.rion-tech.net">www.rion-tech.net</a>
Product specifications are to upgrade or change, without prior notice!





d bytes,

fixed 00



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