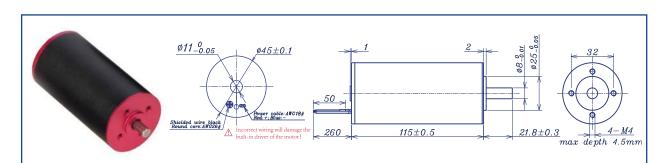


## AM-PI45115AN SERIES (Built-In Position Control)



	Brushless Servo Motor		Ball Bearing		
Motor Model		2408			
Nominal voltage	V	24			
Voltage Range	V	21.5~26.5			
No-load holding current	mA	55			
Static holding torque	mN·m	65.0			
Static holding current	mA	550			
Rated torque	mN·m	65.0			
Rated speed	rpm	8000			
Pulse number / circle	Pulse / circle	256			
Overload torque	mN.m	120.0			
Maximum overload time	second	3			
Moment of inertia	gcm²	109.8			
Weight	g	880			

Additional Information						
Note: Excessive shock loads and periodic oscillations can cause the motor to run unsteadily. Stabilize the system by improving the load.						
Motor thermal resistance:	3.6 K/W	Motor thermal time constant:	1286 S			
Axial (dynamic):	8.0 N	Radial (5mm from head face):	180.0 N			
Press-fit force (static):	100 N	Max allowable screw depth info flange:	4.5 mm			
Maximum radial runout (5mm from the thread surface):	≤0.02 mm	Axial play:	0 (<6.0N)			
Maximum winding temperature	85°C	Ambient temperature range:	-30 to 65 °C			

				Part In	formation		
	Control	function description	on			_	
Input level description VIL max 1.2V; VIH min 22V  Pulse input (red) Falling edge is valid  Direction control (white) High CW Low CCW  Enable input (yellow) VIL Enable			MOTOR 24	HOST	Hz Max. Freq. (Hz)=Rated Speed × (Pulse/Revolve)/6		
				4V Feedback pulse			
				Enable input			
				Pulse input Steering input			
Feedback pulse (green) 32 pulse / rev		Ŭ T	Input GND 本	0 / t			
Input GND (b	Input GND (black) Universal input port				Wiring diagram	Recommended pulse control curve	
	Total Length	LT=L1+L2+L3					
L1:45GP	L1:52GP		L2 :PI45	L3	AM-I	PI45115AN Combiniation Scheme	
62.8	81.0		115.0		<b>←</b>	_L1 →     ←L2 →	
74.8						h	
					G	earbox — Motor —	
					<u>"</u>		
						L <sub>T</sub>	
Note: The o	customer can s	elect the gearbox	to match the m	notor. It is	Recommended Gearl	box:	
recommend	ded to weld mo	tor shaft gears, so			AM-45GP AM-52GP		
here for reference.					For more combination specs, visit Assun Motor w		

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