

BS-IU203-xy-D6EW Inertial Measurement Unit Instructions for use

1. Product overview

BS-IU203-xy-D6EW is an inertial measurement unit (IMU) based on micromachining technology (MEMS), with built-in high-performance MEMS gyroscope and MEMS accelerometer, outputting 3 angular velocities and 3 accelerations.

The BS-IU203-xy-D6EW features high reliability and strong environmental adaptability. By matching different software, the product can be widely used in tactical and industrial UAV, smart ammunition, seeker and other fields.

2. Product features

- 1) Three-axis digital gyroscope:
 - a) $\pm 500^{\circ}/\text{s}$ (Max: $\pm 2000^{\circ}/\text{s}$) dynamic measurement range;
 - b) Zero bias stability: $8^{\circ}/\text{H}$ (GJB, 10s), $1.9^{\circ}/\text{H}$ (ALLAN);
- 2) Triaxial digital accelerometer:
 - a) $\pm 16 \text{ G}$ (Max: $\pm 200 \text{ G}$) dynamic measuring range;
 - b) Zero-bias stability: 0.5 mg (GJB, 10s), 0.1 mg (ALLAN);
- 3) High reliability: MTBF > 20000h;
- 4) Guaranteed accuracy within the full temperature range ($-40^{\circ}\text{C} \sim 80^{\circ}\text{C}$): built-in high-performance temperature calibration and compensation algorithm;
- 5) Suitable for working under strong vibration conditions
- 6) Overload resistant up to 20000 G
- 7) Interface 1-way RS422

3. Field of application

- 1) Tactical and Industrial UAV
- 2) Smart Munitions
- 3) Seeker

Part numbers: BS-IU203-**xy**-D6EC where BS-IU203 - series; -D6EC - digital output, encapsulated

x - gyroscope options, **y** - accelerometer options

To see all models available please go to the end of the specification.

4. Product indicators

Table 1 Technical Index

| Parameter | | Test conditions | BS-IU203-1y | BS-IU203-2y | BS-IU203-3y | Unit |
|------------------|---------------------------------------|---|---|-------------|-------------|---------------------|
| Angular velocity | Range | Turntable | 500 | 1000 | 2000 | $^{\circ}/\text{s}$ |
| | Zero bias | 10 s average, $+70^{\circ}\text{C}$, $+20^{\circ}\text{C}$, -40°C | 8 | 12 | 16 | $^{\circ}/\text{h}$ |
| | | Allan variance, $+20^{\circ}\text{C}$ | 1.9 | 2.85 | 3.8 | $^{\circ}/\text{h}$ |
| | Repeatability of successive starts | $+70^{\circ}\text{C}$ 、 $+20^{\circ}\text{C}$ 、 -40°C | 15 | 22.5 | 30 | $^{\circ}/\text{h}$ |
| | Daily start repeatability | $+70^{\circ}\text{C}$ 、 $+20^{\circ}\text{C}$ 、 -40°C | 30 | 45 | 60 | $^{\circ}/\text{h}$ |
| | Monthly Start Repeatability | $+70^{\circ}\text{C}$ 、 $+20^{\circ}\text{C}$ 、 -40°C | 60 | 90 | 120 | $^{\circ}/\text{h}$ |
| | Zero-bias total temperature variation | $-40^{\circ}\text{C} \sim +70^{\circ}\text{C}$, $1^{\circ}\text{C}/\text{min}$, 10 s average, 1σ | 0.02 | 0.03 | 0.04 | $^{\circ}/\text{s}$ |
| | Zero bias | Life-cycle change, accelerated testing | 0.15 | 0.225 | 0.3 | $^{\circ}/\text{s}$ |
| | Scale | Repeatability of | $+70^{\circ}\text{C}$ 、 $+20^{\circ}\text{C}$ 、 -40°C | 100 | 150 | 200 |
| | | | | | | ppm |

| Parameter | | Test conditions | Typical value | | | Unit |
|---------------------------|------------------------------|---------------------------------------|---|----------------|-----------------|---------------|
| Acceleration | factor | successive starts | | | | |
| | | Daily start repeatability | +70 °C, +20 °C, -40 °C | 200 | 300 | 400 ppm |
| | | Monthly Start Repeatability | +70 °C, +20 °C, -40 °C | 400 | 600 | 800 ppm |
| | | Non-linearity | +20 °C | 200 | 300 | 400 ppm |
| | | Full temperature change | 1 °C/min, 1σ | 400 | 600 | 800 ppm |
| | | Scale factor | Life-cycle change, accelerated testing | 3000 | 4500 | 6000 ppm |
| | Acceleration sensitive term | | | 8 | 12 | 16 °/h/g |
| | Random walk | | | 0.4 | 0.6 | 0.8 °/Vhr |
| | Noise density | | | 0.008 | 0.012 | 0.016 °/s/VHz |
| | Bandwidth | | 3dB | 200 | | Hz |
| | Data delay | | Excluding transmission time | 5ms | | ms |
| Acceleration Zero bias | Range | | | BS-IU203-xA 16 | BS-IU203-xB 200 | g |
| | Zero bias | Stability | 10 s average, + 70 °C, + 20 °C, -40 °C | 0.5 | | mg |
| | | | Allan variance, + 20 °C | 0.1 | | mg |
| | | Repeatability of successive starts | +70 °C, +20 °C, -40 °C | 0.2 | | mg |
| | | Daily start repeatability | +70 °C, +20 °C, -40 °C | 0.4 | | mg |
| | | Monthly Start Repeatability | +70 °C, +20 °C, -40 °C | 0.8 | | mg |
| | | Zero-bias total temperature variation | -40 °C ~ + 70 °C, 1 °C /min variation | 1.6 | | mg |
| | Acceleration Scale factor | Zero bias | Life-cycle change, accelerated test instead | 5 | | mg |
| | | Repeatability of successive starts | +70 °C, +20 °C, -40 °C | 100 | 1500 | ppm |
| | | Daily start repeatability | +70 °C, +20 °C, -40 °C | 200 | 3000 | ppm |
| | | Monthly Start Repeatability | +70 °C, +20 °C, -40 °C | 400 | 6000 | ppm |
| | | Non-linearity | +20 °C | 200 | 3000 | ppm |
| | | Full temperature change | After full temperature calibration and compensation, 1 °C/min, 10 s average peak-peak value | 400 | 6000 | ppm |
| | | Scale factor | Life-cycle change, accelerated test instead | 3000 | 45000 | ppm |
| | | Bandwidth | 3dB | 200 | | Hz |
| | Data delay | | Excluding transmission | 5ms | | ms |

| Parameter | Test conditions | Typical value | Unit |
|--|---|---------------------------------|------|
| | time | | |
| Start time | Time from power up to output valid data | 500 | ms |
| Reset time | Time from reset to output valid data (hard reset) | 500 | ms |
| | Time from reset to output valid data (soft reset) | 300 | ms |
| 3 gyro axes and 3 acceleration axes The degree of nonorthogonality between any two axes | +70°C、+20°C、-40°C | 0.05 | ° |
| Power supply | | 5±0.1 | V |
| Power consumption | | 0.8 | W |
| Communication update rate | 1-way RS422 | 500 (default) 1000 (Max) | Hz |
| Communication baud rate | 1-way RS422 | 460.8 (default) 921.6 (Max.) | kbps |

5. Electrical interface

Table 2 Electrical Definition Table

| Color | Name | Type | Description |
|--------|-------|--------------|------------------------------|
| Red | 5V | Power source | |
| Black | GND | Power source | |
| White | R+ | Input | RS422, 460800 bps by default |
| Brown | R- | Input | |
| Green | T- | Output | |
| Yellow | T+ | Output | |
| Orange | Spare | | |
| Blue | Spare | | |

6. Fabric interface

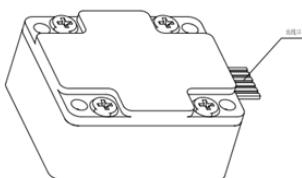
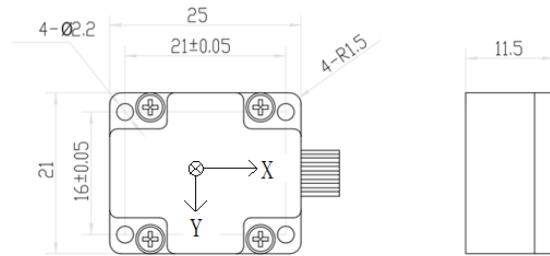


Fig. 1 Schematic diagram of structure outline

7. Instructions for use

7.1. UART reads and writes data

7.1.1. Interface

Default configuration: 460800bps, 8 data bits, 1stop bit, no parity;

7.1.2. Configuration commands

- 1) \$GPENB
Enable UART power-on automatic output
- 2) \$GPDIS
Close UART power-on automatic output
- 3) \$GPSER
View the serial number
- 4) \$GPINF
View configuration information

7.1.3. Protocol format

It is divided into protocol head, protocol body and protocol tail; 500 Hz; the coordinate axis is defined as front right bottom.

Table 3 Software protocol table

| Agree ment | Byte sequenc e number | Data | Unit | Data type | Remark |
|---------------------|--------------------------------|-------------|------|--------------|--------|
| Protoco l header | 0 | 0x5a | | | |
| | 1 | 0x5a | | | |
| Protoco l body | 2~5 | X-axis gyro | °/s | float | |
| | 6~9 | Y-axis gyro | °/s | float | |
| | 10~13 | Z-axis gyro | °/s | float | |

| | | | | | |
|------------------|-------|-------------------|----|-------|---|
| | 14~17 | X-axis plus table | g | float | |
| | 18~21 | Y-axis plus table | g | float | |
| | 22~25 | Z-axis plus table | g | float | |
| | 26~29 | Spare | | | |
| | 30~33 | Spare | | | |
| | 34~37 | Spare | | | |
| | 38~41 | Spare | | | |
| | 42~45 | Spare | | | |
| | 46~49 | Temperatur e | °C | float | |
| | 50~53 | Spare | | | |
| | 54~57 | Spare | | | |
| End of agreement | 58 | Checksum | | | Accumulate and sum 2 to 57 bytes, take the low byte |

All models available:

BS-IU203-1A-D6EW - gyro 500 °/s, accelerometer 16 g
 BS-IU203-1B-D6EW - gyro 500 °/s, accelerometer 200 g
 BS-IU203-2A-D6EW - gyro 1000 °/s, accelerometer 16 g
 BS-IU203-2B-D6EW - gyro 1000 °/s, accelerometer 200 g
 BS-IU203-3A-D6EW - gyro 2000 °/s, accelerometer 16 g
 BS-IU203-3B-D6EW - gyro 2000 °/s, accelerometer 200 g